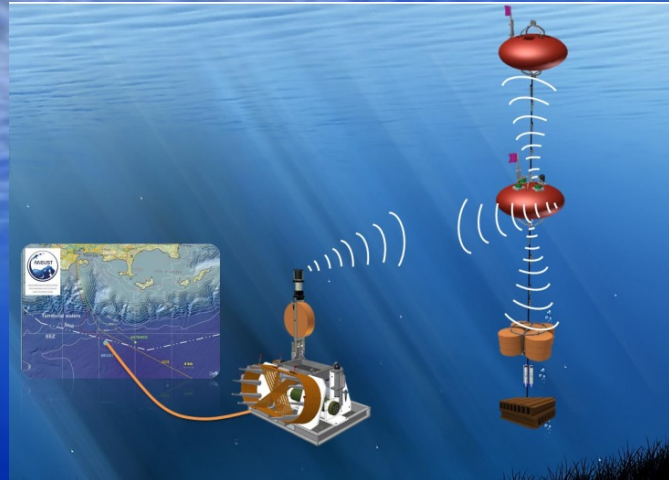
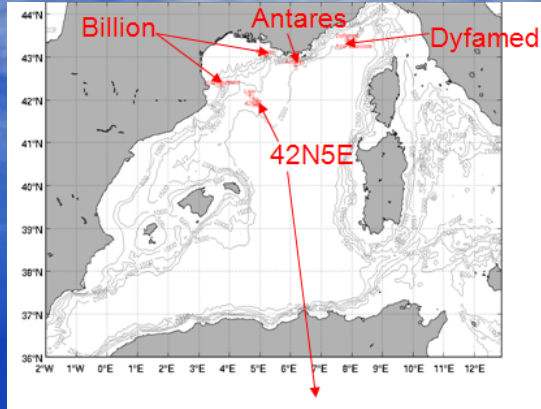
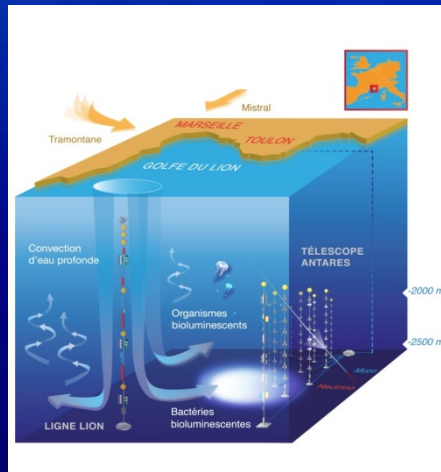


The Observing Long Term Strategy MOOSE & EMSO



P, Theta, Salinity, O₂
High frequency, real time
500-2400 m



P, Theta, Salinity, O₂, BGC
variables
Monthly, Water column



How to Validate this time series ?

Time series

- Requires that each sensor is calibrated

For each depth
 $\text{Var}=f(t)$

Predeployment
Sensors mounted on
CTD
1D Profile with steps
30 points required
encompassing depth of
time series

Monthly Profile

- Requires that each sensor is calibrated
- Requires discrete sampling

For each month
 $\text{Var}=f(Z)$

Postdeployment
Sensors mounted on
CTD
1D Profile with steps
30 points required
encompassing depth of
time series



Profiling.

→ Sampling

→ Analysing

→ Qualifying



$[O_2]=f(Z)$ @ 12 Z each month

$[O_2] = f(\text{volt, SOC, offset, pCorr})$
24 hz averaged @ 1 m resolution
With adjusted parameters

Procedure based on application note
Murphy et al.
64, 64-1, 64-2 64-3

$O_2=f(Z)$ @ 1 m resolution

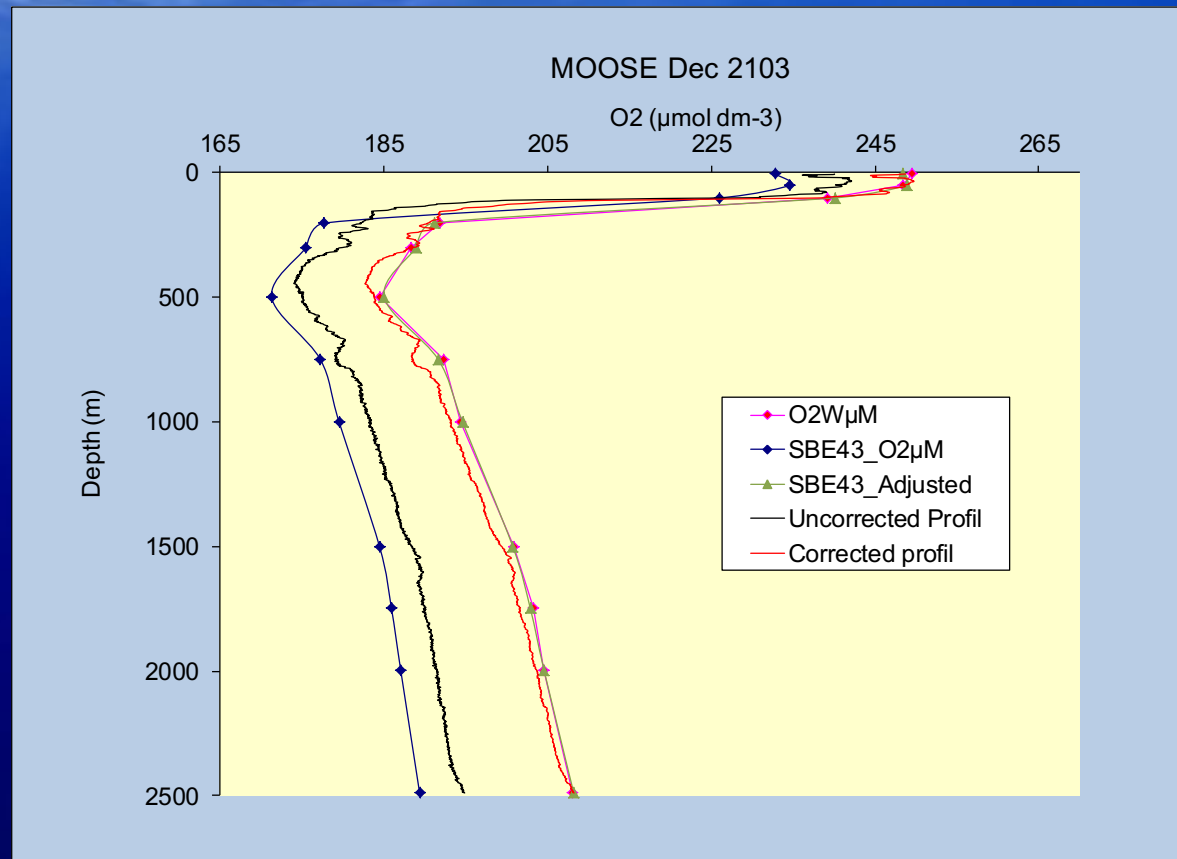
[http://www.seabird.com/application-
notes](http://www.seabird.com/application-notes)

- CTD Dyfamed Moose GE
- 3 palliers : 1000 ; 350 et 5 m
- ODO

- CTD LION Moose GE
- 3 palliers : 1000 ; 350 et 5 m
- CTD peacetime
- CTD ALBATROSS 2014 ; 2015 ; 2016 ; 2017

Procédure pré déploiement – post déploiement Comparaison in situ

Calibration avec l'échantillon Winkler:
Propagation au profil descendant (propagation d'erreur: +/- 2 μ M)



- CTD Rosette data @ 24Hz
 - Extract each steps

- Microcat ODO @ 1/60 Hz
 - Extract each steps



- CTD SBE43 is validated against Winkler samples
- Merge data
- Fit trendline in each time series of 30 mins
- Sample both time series with same time stamp
- Compute offset averages

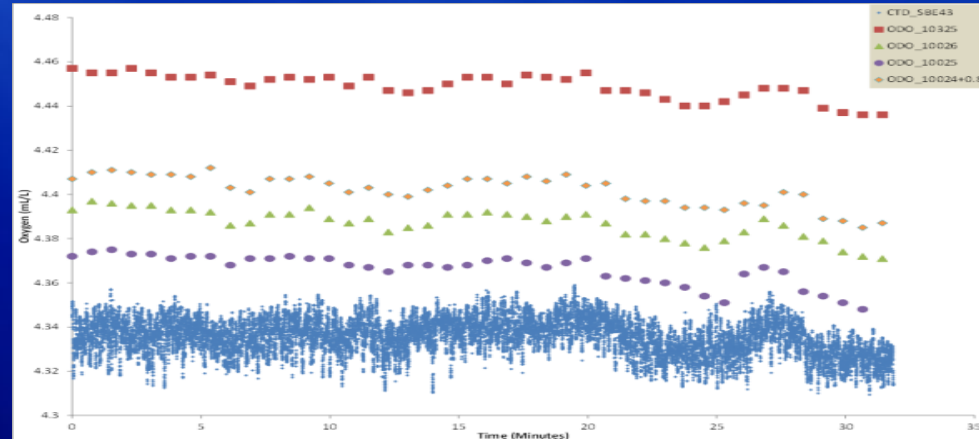
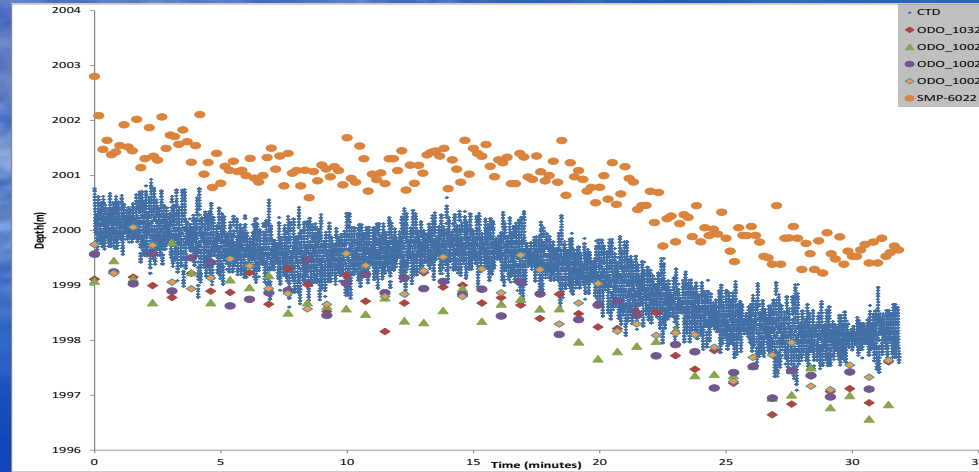
Data acquisition CTD

Sensors @ 2 depths (5 and 2000 m) Time series of available parameters

30-45 mins



Microcat mounted on CTD carousel



Co variability, offset

→ correction pre-deployment

→ correction post-deployment

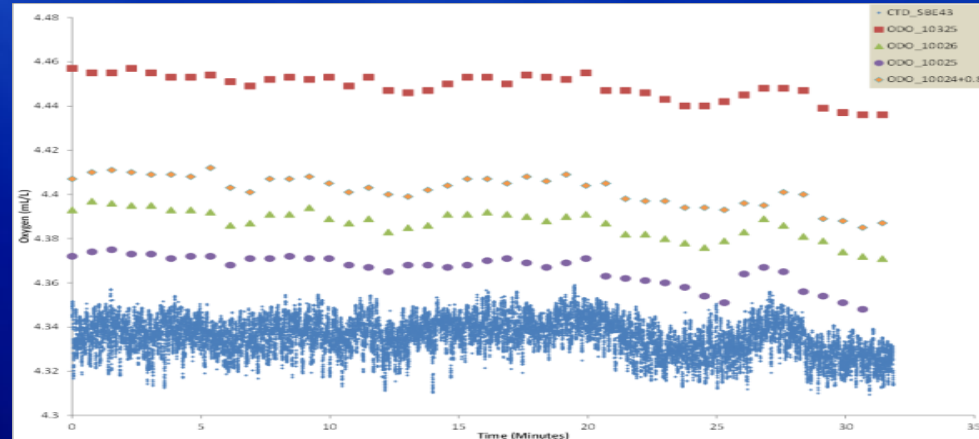
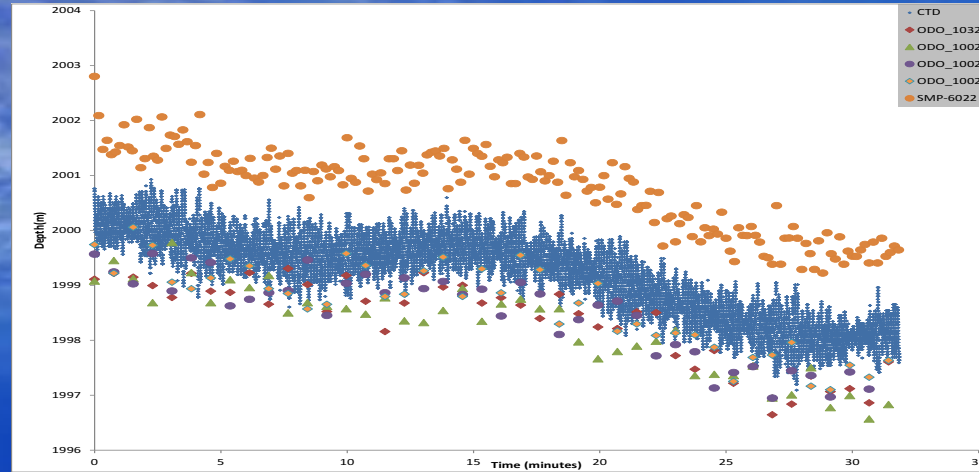
and then drift correction to apply on acquired data =set

Data acquisition CTD
Sensors @ 2 depths (5 and 2000 m)
30-45 mins



Microcat mounted on CTD carousel

Time series of available parameters (Pressure ; Conductivity)



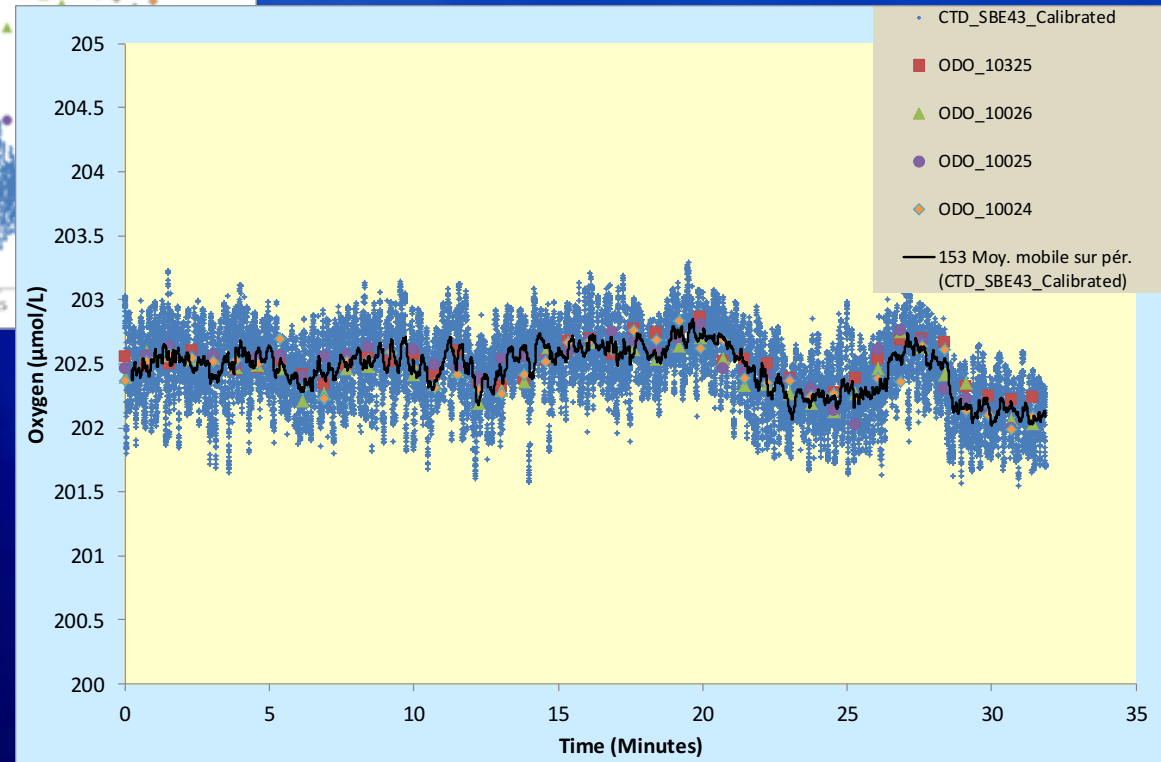
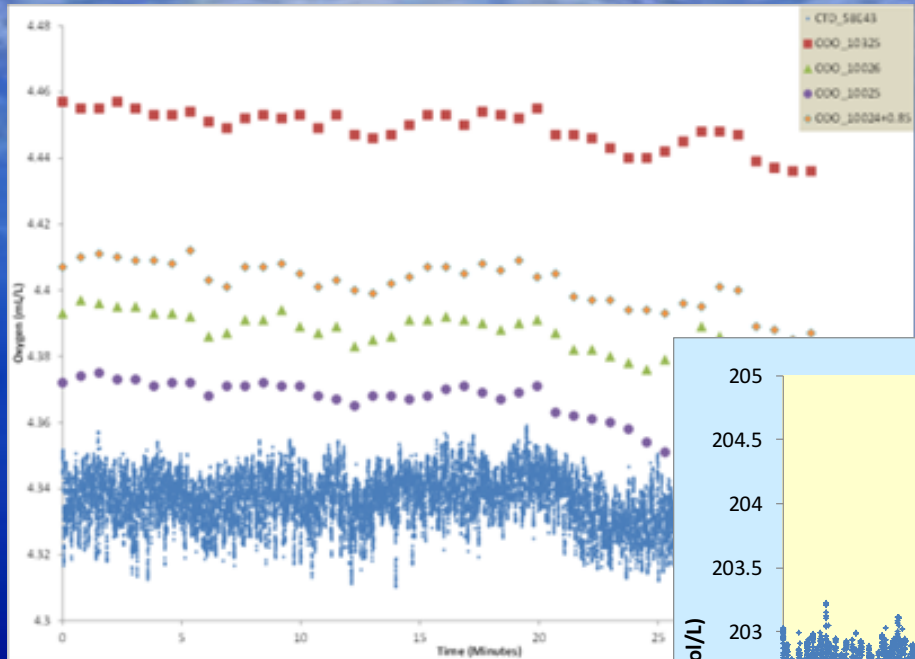
Co variability, offset

→ correction pre-deployment

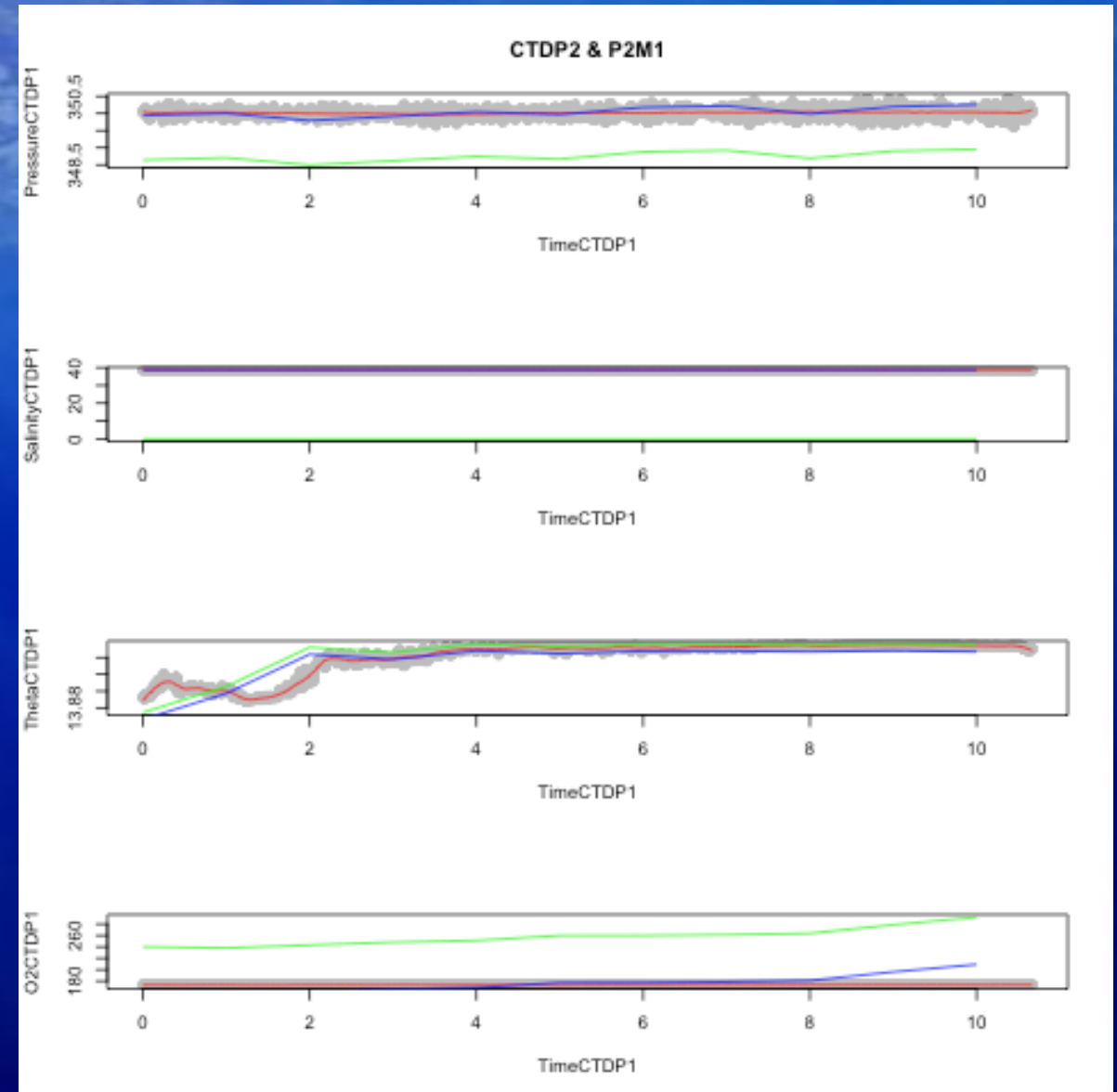
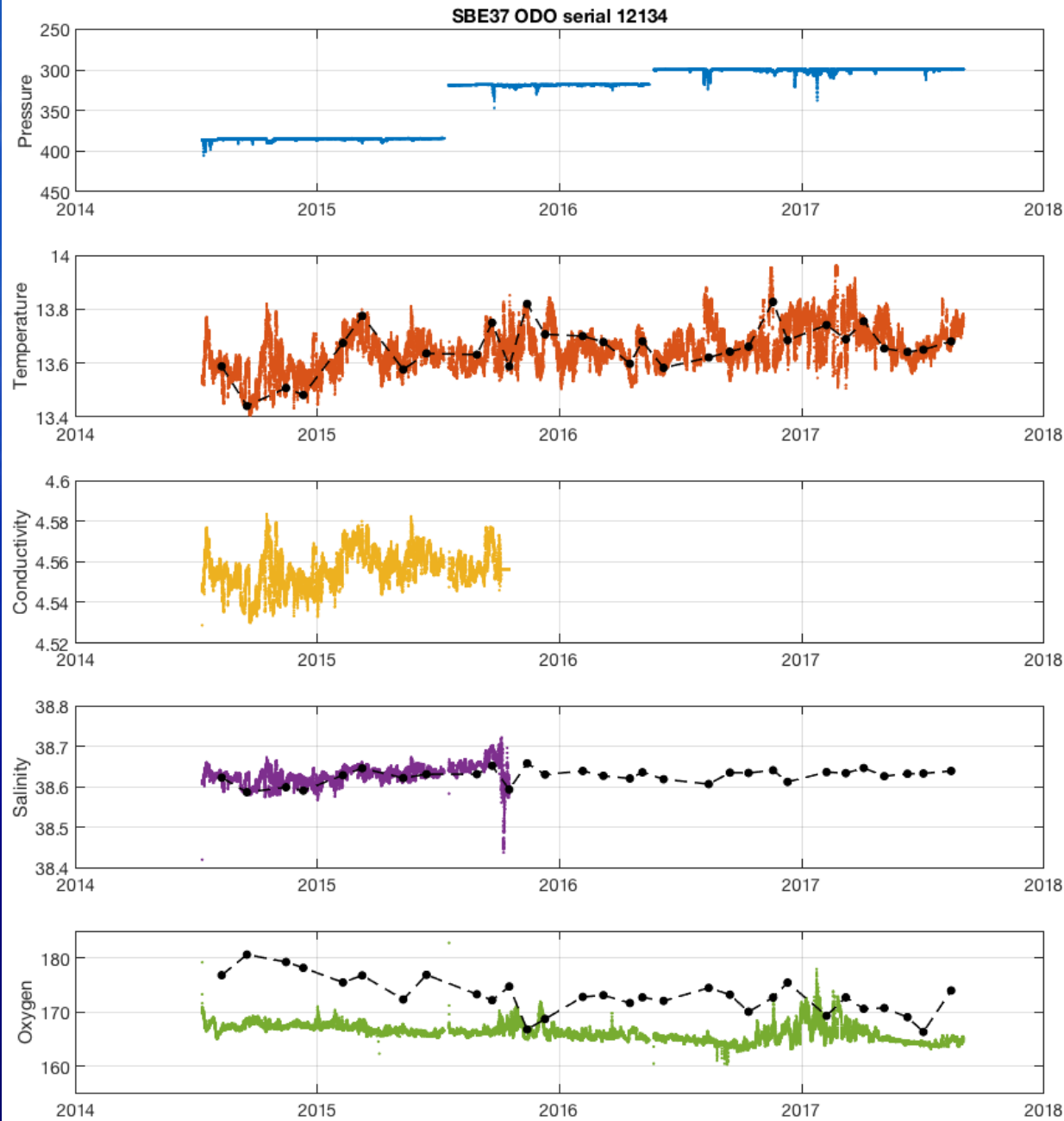
→ correction post-deployment

and then drift correction to apply on acquired data =set

- 1) Fit a LOESS function for each time series
- 2) Compute offset from average distance during the «standby» @ lower acquisition frequency
- 3) Apply specific offset to each sensor

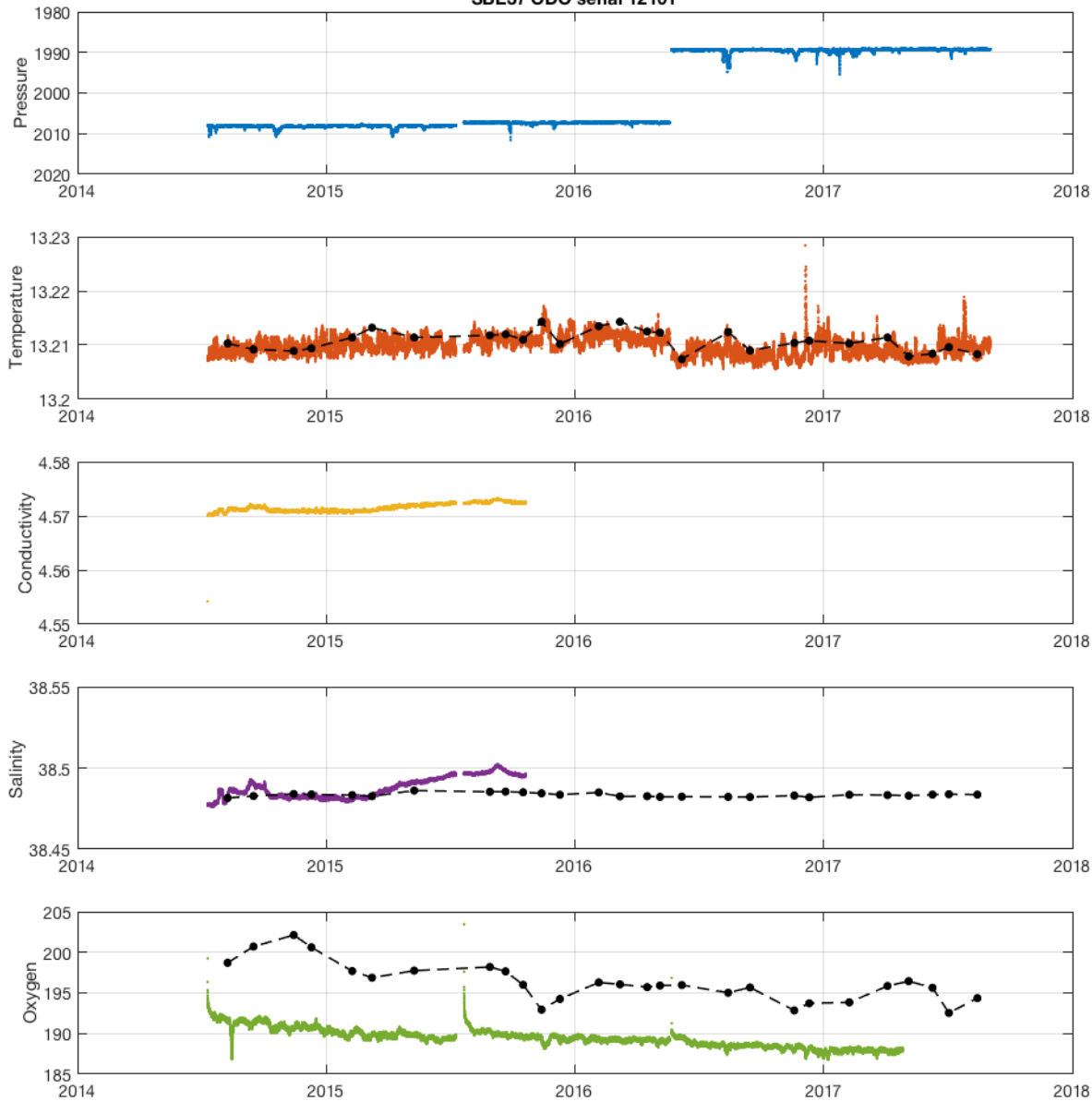


DYFAMED 2016-2017 – 350 m

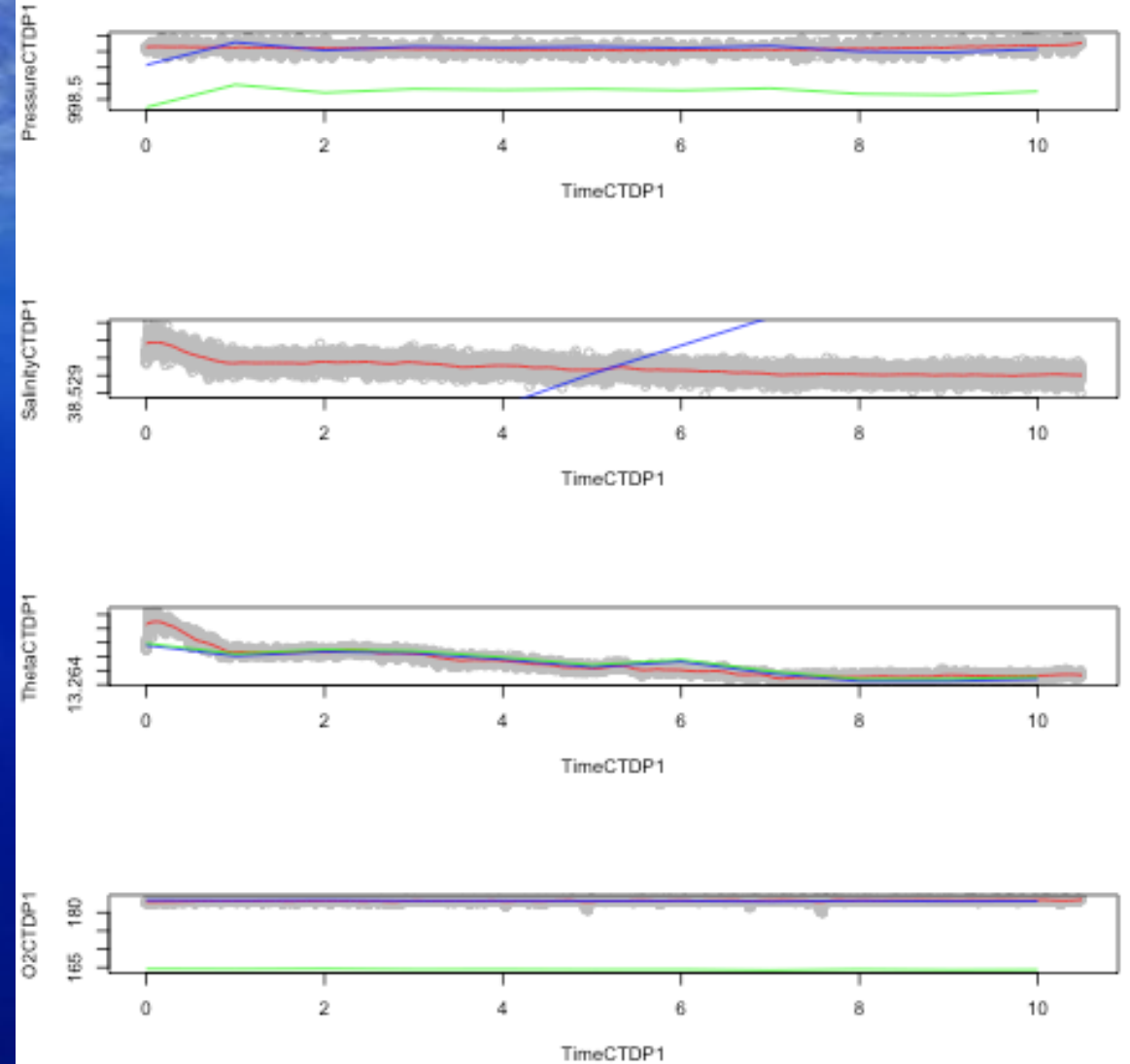


DYFAMED 2016-2017 – 2000 m

SBE37 ODO serial 12101



CTDP1 & P1M2



DYFAMED 2016 2017 – 350 m

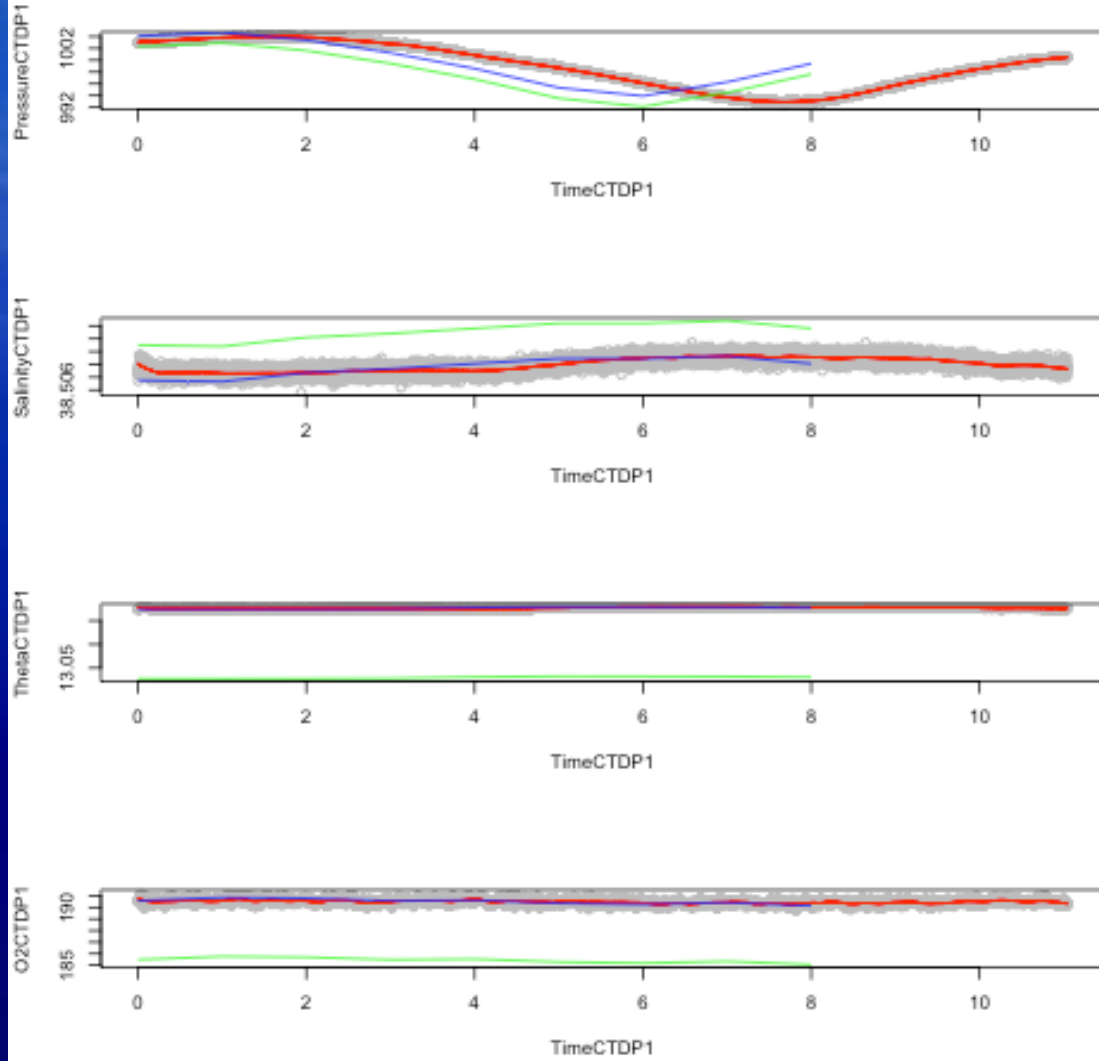
	DeltaOx	DeltaSalinity	DeltaTheta	DeltaPressure
ODO 12134	82.66	-38.62	0.004	-1.30
ODO 12101	-19.03	11.59	0.004	-0.96

DYFAMED 2016 2017 – 1000 m

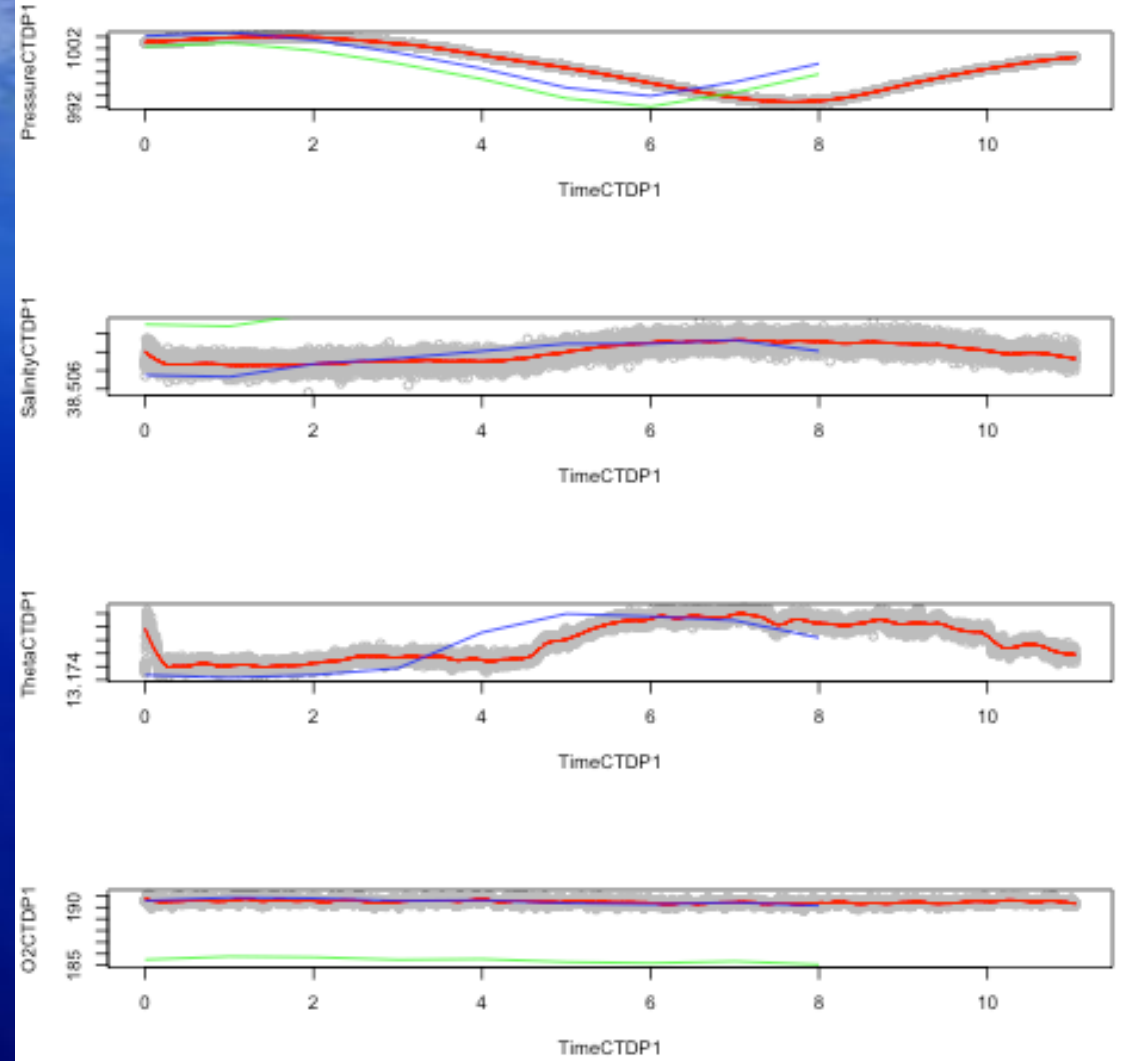
	DeltaOx	DeltaSalinity	DeltaTheta	DeltaPressure
ODO 12134	82.66	-38.62	0.004	-1.30
ODO 12101	-19.03	11.59	0.004	-0.96

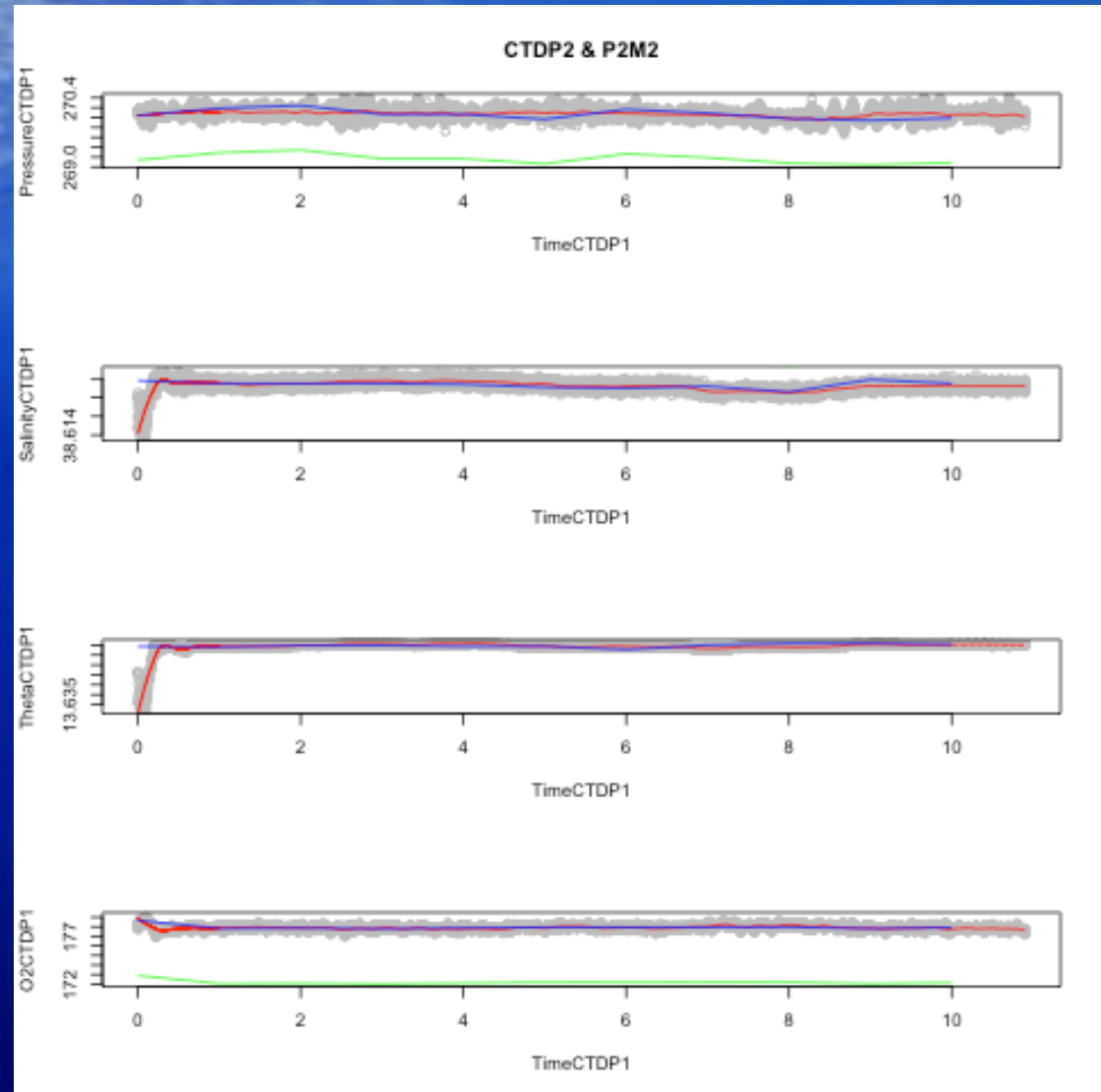
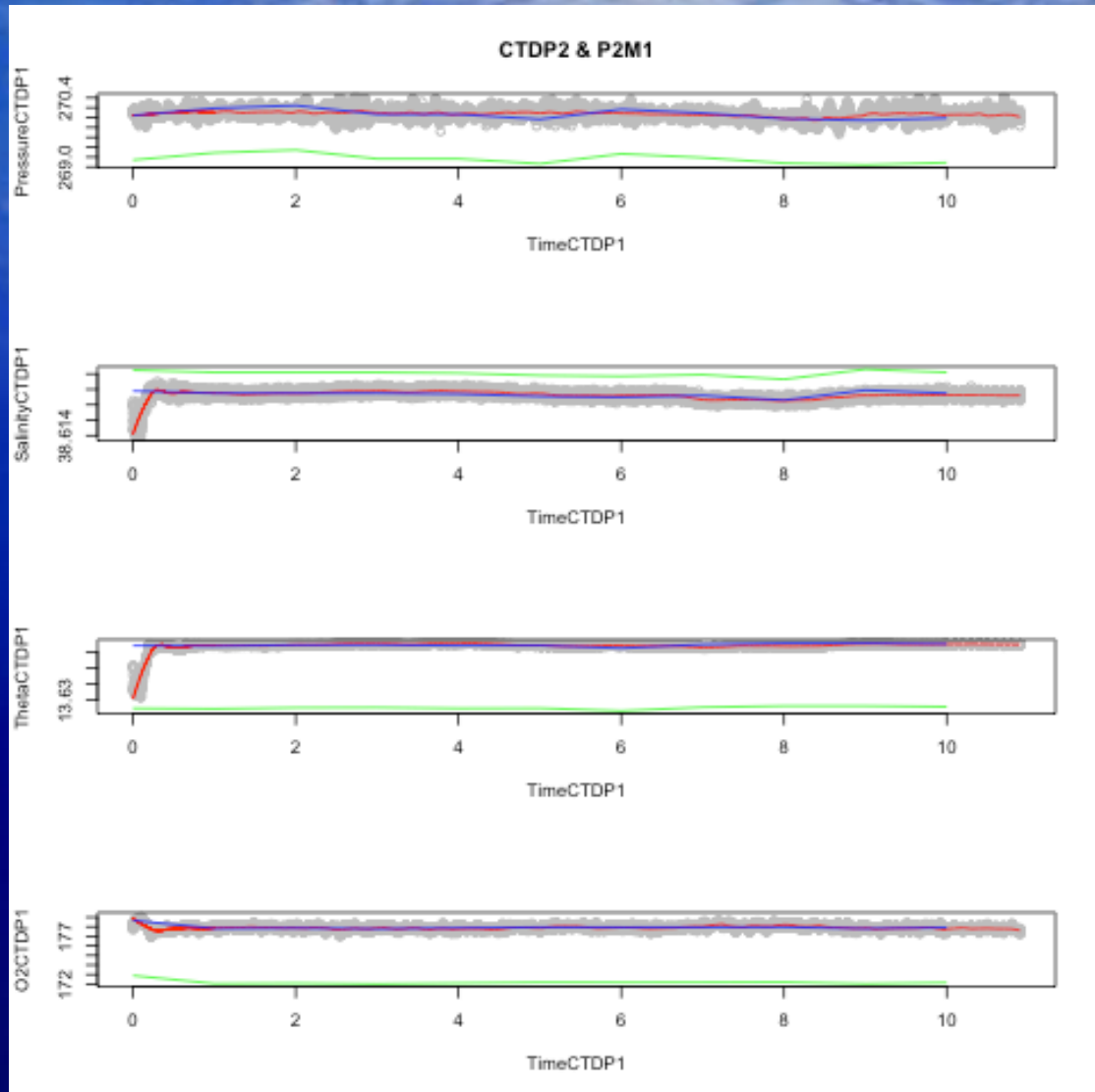
LION. 2016 2017 – 1000 m

CTDP1 & P1M1



CTDP1 & P1M2





LION 2016 2017 – 5 m

	DeltaOx	DeltaSalinity	DeltaTheta	DeltaPressure
ODO 9791	-7.810	0.004	-0.003	-0.304
ODO 10757	-13.645	-0.004	-0.006	-0.856

LION 2016 2017 – 300 m

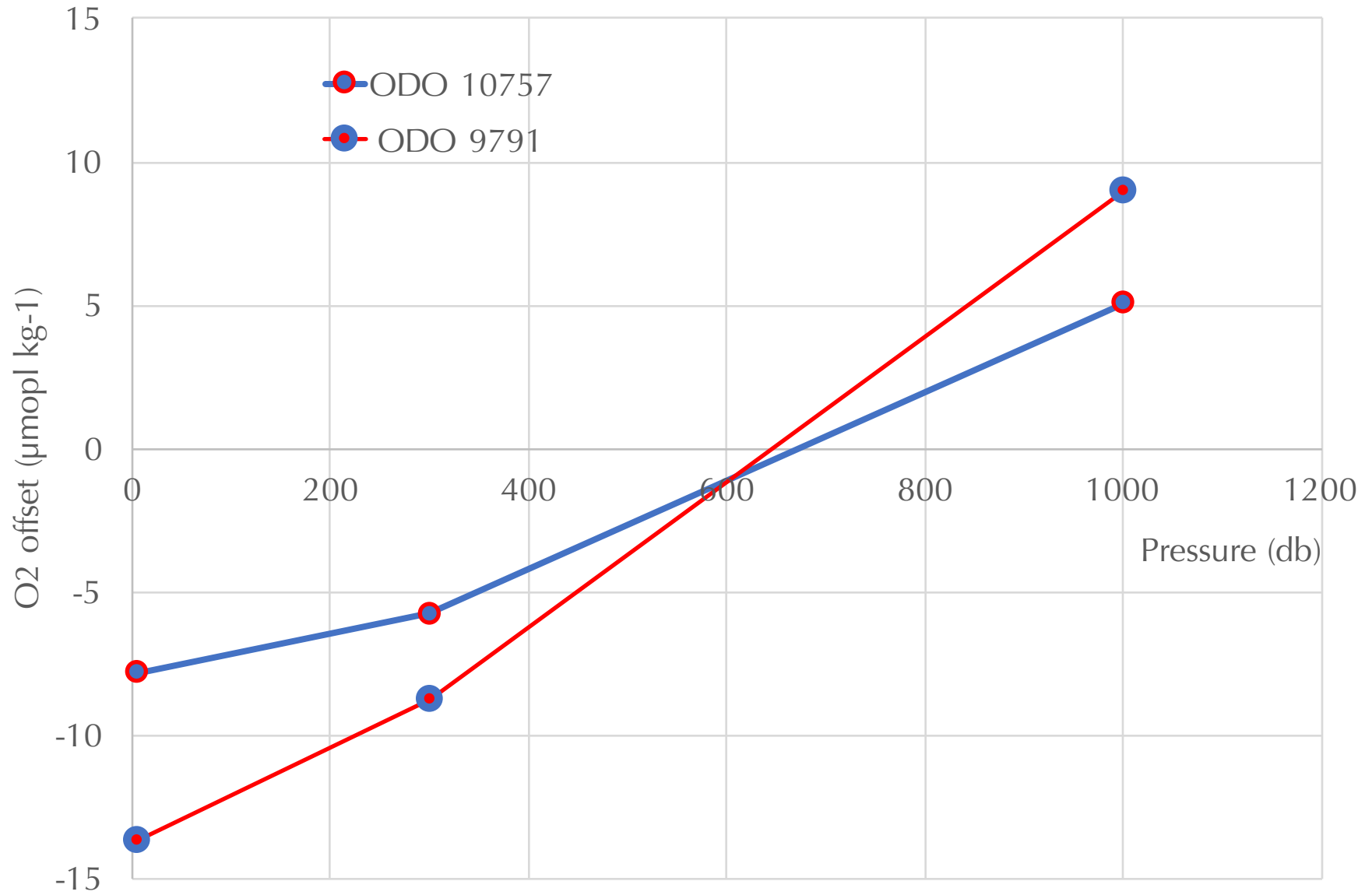
	DeltaOx	DeltaSalinity	DeltaTheta	DeltaPressure
ODO 9791	-5.774	0.003	-0.040	-0.901
ODO 10757	-8.719	-0.006	-0.067	-0.866

LION 2016 2017 – 1000 m

	DeltaOx	DeltaSalinity	DeltaTheta	DeltaPressure
ODO 9791	5.057	-0.003	0.147	1.125
ODO 10757	9.005	0.007	0.147	0.900



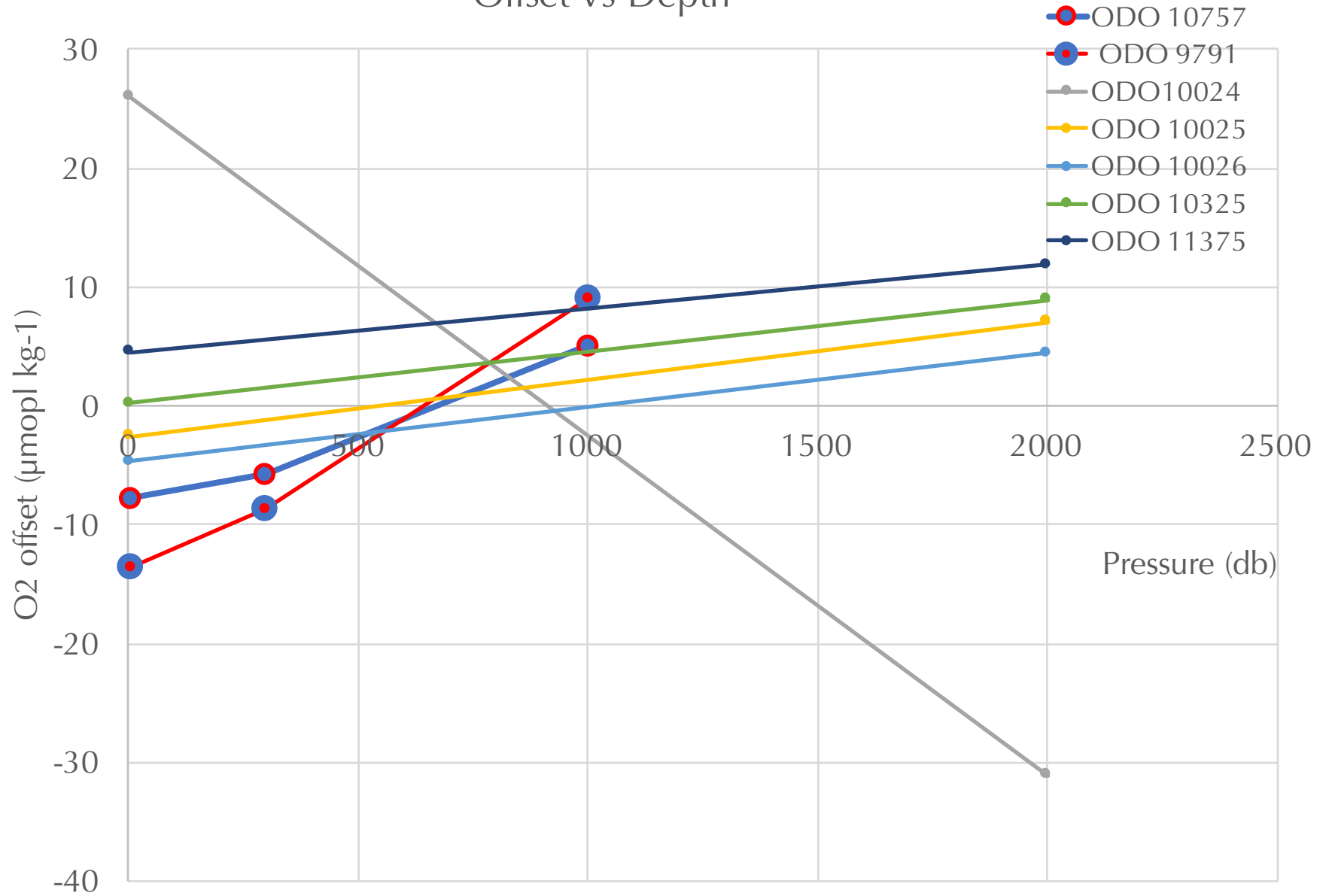
Offset vs Depth



Pressure Offset

	DeltaOx10024	DeltaOx10025	DeltaOx10026	DeltaOx10325	DeltaOx11375
Pallier_2000	-31.102	7.025	4.480	8.919	11.886
Pallier_5	26.012	-2.559	-4.668	0.212	4.552

Offset vs Depth



Offset time evolution

	DeltaO210024	DeltaO210025	DeltaO210325	DeltaO210325
Predeployment	34.99	1.35	2.28	5.05
Postdeployment	35.44	3.49	0.16	4.52
Daily drift (300 days) $\mu\text{mol O}_2 \text{ kg}^{-1} \text{ d}^{-1}$	0.0015	0.0071	-0.0071	-0.0018

Apply a drift over time of deployment

Offset evolution ($\mu\text{mol O}_2 \text{ kg}^{-1}$)

Sensor #	9794	15637	15638	15639
5m	8.16	11.84	12.98	12.12
	-1.45	7.96	8.20	8.68
daily drift $\mu\text{mol O}_2 \text{ kg}^{-1} \text{ d}^{-1}$ 26 days	-0.37	-0.15	-0.18	-0.13
1000m	8.94	14.83	15.95	15.85
	0.97	11.77	11.89	12.60
daily drift $\mu\text{mol O}_2 \text{ kg}^{-1} \text{ d}^{-1}$ 26 days	-0.31	-0.12	-0.16	-0.13

Conclusion

- If pre & post deployment
 - Apparent Sensor Drift can be assessed

- Steps @ various depth
 - Offset evolution is not understood
 - IDEAS ?